

1 **Application of Classical Kalman filtering technique in assimilation of**
2 **multiple data types to NeQuick model**

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14 **Abstract**

15 This study attempts to improve estimation of ionospheric electron density profiles over
16 Korea and adjacent areas by employing classical Kalman filtering technique to
17 assimilate Total Electron Content (TEC) data from various sources into the NeQuick
18 model. Successive corrections method was applied to spread the effect of TEC data
19 assimilation at a given location to others that lacked TEC observations. In order to
20 reveal that the assimilation results emulate the complex ionospheric changes during
21 geomagnetic storms, the selected study days included both quiet ($K_p \leq 3$) and disturbed
22 geomagnetic conditions in the year 2015. The results showed that assimilation of TEC
23 data derived from ground-based GPS receivers can improve the root mean squared
24 error (RMSE) associated with the NeQuick model estimation of ionospheric parameters
25 by ≥ 56 %. The improvement of RMSE achieved by assimilating TEC data that were
26 measured using ionosondes was ~ 50 %. The assimilation of TEC observations made by
27 the COSMIC radio occultation technique yielded results that depicted RMSE
28 improvement of > 10 %. The assimilation of TEC data measured by GPS receiver

1 onboard Low Earth Orbiting satellites yielded results that revealed deterioration of
2 RMSE. This outcome might be due to either the fact that the receivers are on moving
3 platforms and these dynamics might have not been accounted for during TEC
4 computation or limitation of the assimilation process. Validation of our assimilation
5 results with global ionosphere TEC data maps as processed at the center for orbit
6 determination in Europe (CODE) revealed that both depicted similar TEC changes,
7 showing response to a geomagnetic storm.

8 *Keywords:* Ionosphere, modeling, data assimilation, NeQuick, Geomagnetic storms
9

10 **1. Introduction**

11

12 The peak electron density in the *F2*-region (NmF2) and total electron content (TEC) are
13 widely used parameters to characterize the ionosphere (Rishbeth and Garriott, 1969;
14 Gerzen et al. 2013). The NmF2 affects high-frequency (3 – 30 MHz) radio wave
15 communication applications. For instance, Geeta and Yudav, (2014) stated that for
16 frequencies lower than 30 MHz, the ionosphere acts as a helpful aid for the radio wave
17 propagation, but for the frequencies slightly greater than 30 MHz, it may cause
18 attenuation. The TEC affects Global Navigation Satellite System (GNSS) based
19 positioning by introducing ionospheric refraction (Hofmann-Wellenhof et al., 2007) in
20 which the code delay or carrier phase advance occurs, resulting into a pseudo-range
21 measurement instead of a true range measurement.

22 Several research efforts have tried to model NmF2 and TEC. For instance, the
23 Committee on Space Research and the International Union of Radio Science formed a
24 working group in the late sixties to produce an empirical standard model of the
25 ionosphere, the International Reference Ionosphere (IRI), based on all available data
26 sources (Bilitza et al. 1993). Output of the IRI includes NmF2 and TEC, among other
27 parameters. The NeQuick is another global ionospheric model that can be used to
28 obtain NmF2 and TEC. The NeQuick model and its subsequent modifications (NeQuick

1 G and NeQuick 2) are a three-dimensional, time dependent ionospheric electron density
2 model developed by the Abdus Salam International Center for Theoretical Physics
3 (ICTP) in Trieste, Italy and the Institute for Geophysics, Astrophysics and Meteorology
4 of the University of Graz, Austria (Nava et al. 2008, and references therein).

5 In order to produce a good empirical model of the ionosphere over a region, there is
6 need to have extensive observations to be used for constructing the model. It may be
7 difficult to obtain adequate observations that can be used in modeling since maintaining
8 stable and reliable ground-based instruments all over regions may be expensive or not
9 practicable, particularly over the seas and deserts. It is now known that estimations of
10 ionospheric parameters by empirical and theoretical models may be improved by
11 assimilating observations to the model.

12 Bust et al., (2004) presented the Ionospheric Data Assimilation Three-Dimensional
13 (IDA3D) algorithm which uses a three-dimensional variational data assimilation
14 technique (3DVAR). The IDA3D is capable of incorporating most electron density
15 related measurements including GNSS-TEC measurements, low-Earth-orbiting beacon
16 TEC, and electron density measurements from radars and satellites. Bust and Datta-
17 Barua, (2013) stated that Ionospheric Data Assimilation Four-Dimensional (IDA4D) is an
18 ionospheric data assimilation algorithm which provides global 3-D time-evolving maps of
19 ionospheric electron density. A computationally practical data assimilation technique
20 known as Best Linear Unbiased Estimator (BLUE) has been implemented by Angling
21 and Cannon (2004) for combining RO data with background ionospheric models.
22 Recently, Mengist et al. (2019), investigated the IDA4D technique over Korea and the
23 neighboring areas, considering IRI model as the background. They showed that
24 assimilation of ground-based global positioning system (GPS) Slant TEC (STEC),
25 NmF2 obtained from Constellation Observing System for Meteorology, Ionosphere and
26 Climate (COSMIC) radio occultation (RO) and ionosondes yielded the best results.
27 Ssessanga et al. (2019) presented a preliminary study that assessed the capability of
28 their developed four-dimensional (in space and time) data assimilation scheme to more
29 accurately estimate the 3-D picture of the ionosphere over the South African region.

1 Yue et al. (2007) assimilated electron densities observed by the Millstone Hill incoherent
2 scatter radar (ISR) into a one-dimensional midlatitude ionospheric theoretical model by
3 using an ensemble Kalman filter (EnKF) technique.

4 The current study performed assimilation of TEC derived from ground-based GPS
5 receiver and ionosonde stations as well as COSMIC RO to the NeQuick model.
6 Moreover, the study assimilated the TEC derived from GPS receivers onboard Low
7 Earth Orbiting (LEO) Swarm and COSMIC satellites. The classical Kalman filtering
8 technique applied to assimilate TEC observations to NeQuick model and the successive
9 corrections method used to correct the NeQuick model generated ionospheric
10 parameters at locations and epochs that lacked TEC observations make this study
11 unique. After describing in section 2 the data used in this work, we present in sections 3
12 and 4 the classical Kalman filtering technique and the successive corrections method,
13 respectively. The results and discussions are presented in section 5, while the
14 conclusions are presented in section 6.

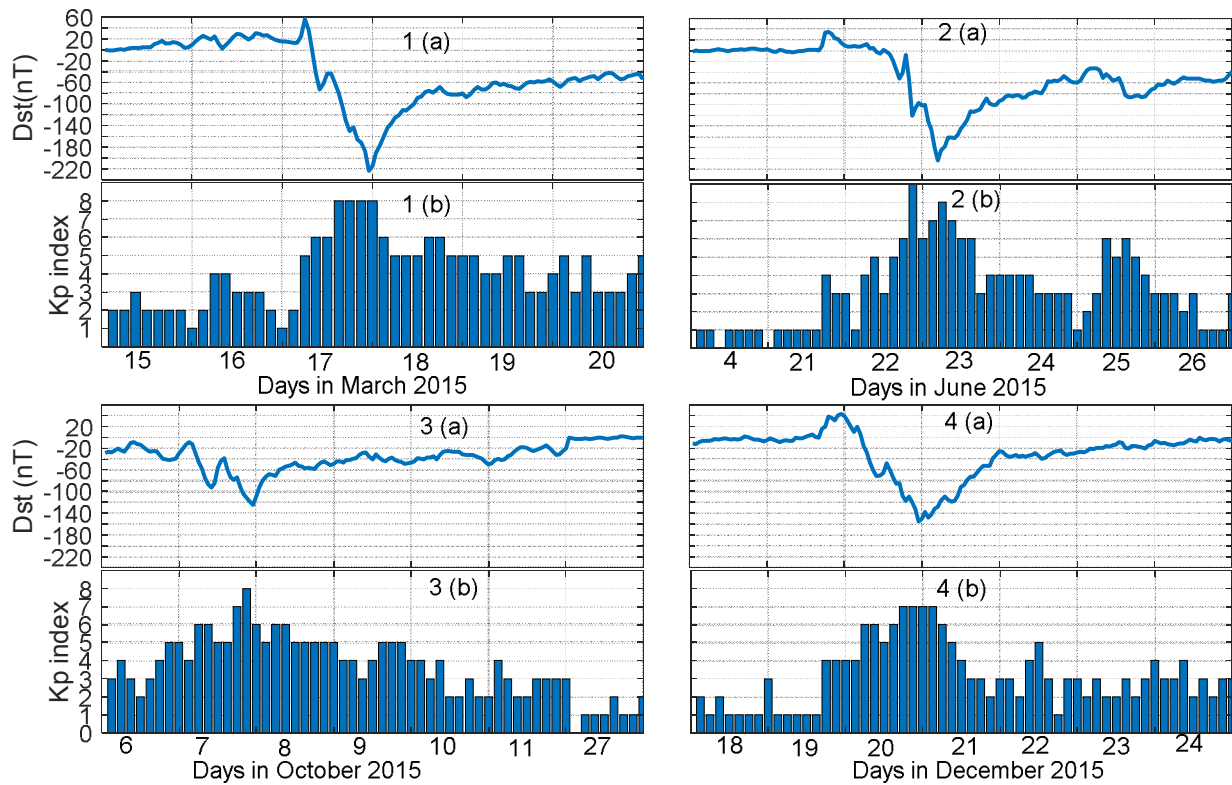
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16 **2. Data sources**

17 During geomagnetic storms, the variations in zonal electric fields and composition of the
18 neutral atmosphere contribute significantly to the occurrence of negative and positive
19 ionospheric storm effects (Risbeth and Garriot, 1969; Buonsanto, 1999). In order to
20 ascertain the ability of the assimilation results to emulate the complex ionospheric
21 changes during geomagnetic storms, the assimilations were done during March 15 –
22 20, June 4, 21 – 26, October 6 – 11, 27, and December 18 – 24, 2015. In these four
23 different months, representing seasons of March equinox, June solstice, September
24 equinox, and December solstice, the recorded minimum Dst were -222, -204, -124, and
25 -155 nT, respectively. For purposes of comparing ionospheric parameters on quiet and
26 disturbed geomagnetic conditions, there was one quiet day ($K_p \leq 3$) in each of the
27 selected months. The selected geomagnetically quiet ($K_p \leq 3$) days were March 15,
28 June 4, October 27, and December 18. Figure 1 presents the variation of Dst (panel
29 (a)'s) and K_p indices (panel (b)'s) during the period under study. The hourly Dst and 3

1 hourly Kp indices can be obtained from the World Data Center of Kyoto, Japan
2 (<http://swdcwww.kugi.kyoto-u.ac.jp/>).

3 The pattern of the variation of Dst shown in Figure 1 indicates several main and
4 recovery phases of geomagnetic storms during the period mentioned. The high Kp
5 index values ($Kp > 5$) on March 17 – 18, June 22 – 23, October 7 – 8, and December 20
6 - 21 confirm the occurrence of geomagnetic disturbances during the period. Therefore,
7 the ionosphere might vary greatly in the period under study.



8

9 *Figure 1: Variation of (a) Dst and (b) Kp during (1) March 15 – 20, 2015, (2) June 4, 21*
10 *– 26, 2015, (3) October 6 - 11, 27, 2015, and (4) December 18 – 24, 2015.*

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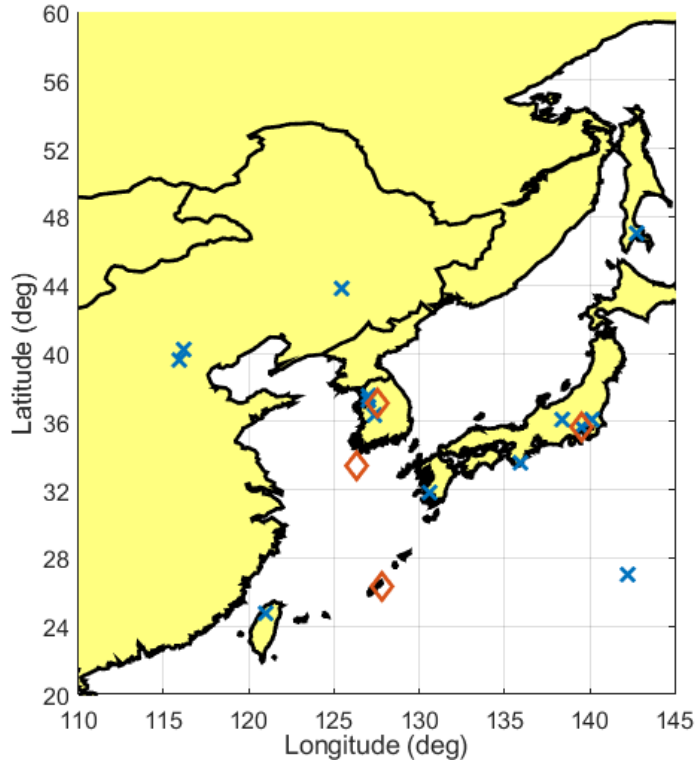
12 Most global climatological ionospheric models such as NeQuick and IRI might not
13 emulate possible rapid variations of the ionosphere due to geomagnetic storms. In order
14 to improve estimation of electron density up to altitude of GPS satellites (~20200 km)
15 during the previously stated disturbed geomagnetic periods, we performed data

1 assimilation to NeQuick model driven by daily F10.7 values. It is important to mention
2 that unlike NeQuick model which can estimate electron density up to altitude of GPS
3 satellites, IRI only estimates it up to an altitude of 2000 km. Moreover, since NeQuick is
4 a quick-run model, it is suitable for data assimilation process as computation time might
5 be reduced.

6 Figure 2 shows with blue crosses and red diamonds the locations of the ground-based
7 GPS receivers and ionosonde stations, respectively, that were used to obtain the TEC
8 data. The stations indicated in the figure had available data during most of the days
9 considered in the study period. Table 1 provides the geophysical parameters (e.g.,
10 geographic and geomagnetic coordinates) associated with the stations in Figure 2. The
11 Receiver Independent (RINEX) data format files of GPS receivers can be obtained from
12 University NAVSTAR Consortium network (<ftp://data-out.unavco.org>). The RINEX files
13 were processed using a software described in Ciruolo et al. (2007), yielding TEC
14 together with other parameters such as time, elevation and azimuth angles, and
15 geographic longitude and latitude of the ionospheric pierce points. The software can
16 produce TEC data at resolutions of 30 seconds, 1, 5, 10 and 15 minutes. To reduce
17 computational burden of working with high resolution TEC data, this study considered 5
18 minutes' resolution data.

19 The TEC derived by integrating electron density profiles obtained from ionosonde
20 stations listed in Table 1 can be accessed from the National Oceanic and Atmospheric
21 Administration (NOAA) website via the link, <ftp://ftp.ngdc.noaa.gov>. The data obtained
22 from the NOAA website was in the form of auto-scaled ionospheric parameters such as
23 peak height in F2-region, foF2, and TEC which are stored in Standard Archiving Output
24 (SAO) format files. The TEC data provided in SAO files have a resolution of 15 minutes
25 and are obtained by integrating electron density profiles up to altitude of ~700 km.
26 Reinisch and Huang, (2001) stated that the auto-scaling program (real-time ionogram
27 scaler with true height (ARTIST)) approximates the electron density profile above the F2
28 layer peak by an α -Chapman function with a constant scale height that is derived from
29 the bottom-side profile shape near the F2 peak. The ionospheric parameters in SAO

1 files are associated with flags showing confidence level which ranges from low (11) to
 2 high (55). The foF2 and TEC data obtained from the SAO files used in this study were
 3 those with high confidence level (≤ 22).



4
 5 **Figure 2:** Locations of GPS (blue crosses) and ionosonde (red diamonds) stations used in the
 6 study

7 Table 1: Geophysical parameters of GPS and ionosonde stations used in the study

Station name	ID	Country	Geog lat ($^{\circ}$)	Geog lon ($^{\circ}$)	mag lat ($^{\circ}$)
GPS receiver stations					
Daejeon	DAEJ	S. Korea	36.40	127.37	30.62
Koganei	KGNI	Japan	35.71	139.49	29.46
Aira	AIRA	Japan	31.82	130.59	25.92
Changchu	CHAN	China	43.79	125.44	38.15
Shimosato Hydrographic	SMST	Japan	33.58	135.94	27.46

Suwon	SUWN	S. Korea	37.27	127.05	31.51
Hsinchu	TCMS	Taiwan	24.79	120.99	19.29
Hsinchu	TNML	Taiwan	24.79	120.99	19.29
Usuda	USUD	Japan	36.13	138.36	29.91
Yongsan	YONS	S. Korea	37.54	127.00	31.78
BJNM, NIM	BJNM	China	40.24	116.22	34.94
Beijing Fangshan	BJFS	China	39.61	115.89	34.31
Yuzhno-Sakhalinsk	YSSK	Russia	47.03	142.71	40.71
Tsukuba 2-A	TSK2	Japan	36.11	140.09	29.85
Chichijima-A	CCJ2	Japan	27.07	142.20	20.96
Ionosonde stations					
Jeju	JJ433	S. Korea	33.43	126.30	27.70
Kokubunji	TO536	Japan	35.70	139.50	29.45
Icheon	IC437	S. Korea	37.10	127.50	31.32
Okinawa	OK426	Japan	26.33	127.80	20.62

1

2 As mentioned in section 1, TEC measurements as obtained from the GPS receivers
3 onboard Swarm and COSMIC satellites were also used. The Swarm constellation is
4 composed of three identical satellites, namely, Alpha (A), Bravo (B), and Charlie (C).
5 Detailed information about orbital characteristics of the Swarm satellites can be found in
6 Zakharenkova and Astafyeva, (2015). Each of the Swarm spacecraft carries a Precision
7 Orbit Determination (POD) antenna. The GPS signal phase measurements as obtained
8 from this antenna can be used to estimate the line of sight TEC between Swarm and
9 GPS satellites. This line of sight TEC data can be freely downloaded from the European
10 Space Agency (ESA) website (<http://www.earth.esa.int/swarm>). Its resolution was 1 and
11 10 seconds after and before July 15, 2014, respectively. The COSMIC TEC data which
12 is based on POD antenna measurements is processed at 1 second resolution and

1 archived at the COSMIC Data Analysis and Archive Centre (CDAAC) (<http://cosmic->
2 io.cosmic.ucar.edu/cdaac/index.html). The line of sight TEC (STEC) obtained from
3 Swarm and COSMIC satellites were converted to vertical TEC (VTEC) at the position of
4 the LEO satellites as in Zhong et al. (2015).

5 The TEC data resulting from integration of electron density profiles associated with
6 COSMIC RO used in this study were also obtained from CDAAC. The integrated
7 electron density (integration being done up to the altitudes of the COSMIC satellites)
8 can be obtained from ionPrf files. The TEC associated with a particular electron density
9 profile was assigned to the geographic coordinate of NmF2 in the same file. The
10 electron density profiles are obtained by the Abel inversion of RO data, assuming local
11 spherical symmetry of the electron density in a large region (a few thousand kilometers
12 in radius) around the ray path tangent points (Krankowski et al. 2011). This assumption
13 may not always be valid, and horizontal ionospheric gradients may significantly affect
14 the retrieved electron density profiles, in particular below the F-layer. In addition, the
15 geographical location of the ray path tangent points at the top and at the bottom of a
16 profile may differ (horizontal smear) by several hundred kilometers. Several studies
17 (e.g. Krankowski et al., 2011 and Mengist et al., 2019) that have used COSMIC data
18 commonly consider measurements with horizontal smear > 1500 km prone to errors and
19 they reject such measurements. Typically, over an area bounded by 5 and 4 degrees'
20 longitude and latitude ranges, respectively, the total number of COSMIC TEC data
21 obtained in a day may be ~3. Therefore, rejection of data may make this number reduce
22 further. The current study did not reject COSMIC TEC with horizontal smear > 1500 km
23 since Mungufeni et al. (2020) analyzed COSMIC TEC data which were coincident with
24 TEC estimated by ionosonde stations over South Africa, finding that, compared to
25 measurements with horizontal smear > 1500 km, some measurements with horizontal
26 smear < 1500 km were far from the linear least squares fitting line.

27

28 **3 The classical Kalman filtering technique**

1 In this study, we considered TEC measurement y at time t_k to improve the NeQuick
 2 model estimate of the ionospheric electron density profile x along the path that contains
 3 electrons that constitute y . We further considered that y is linearly related to x via the
 4 equation (Grewal and Andrews, 2001; Angling and Cannon, 2004),

$$5 \quad y = Hx + w \quad (1)$$

6 where H is the measurement sensitivity matrix and w is the measurement noise. If x
 7 consists of p electron density values, H will be a row matrix with dimension p . As
 8 justified later in this section, elements of H were considered to be vertical grid spans
 9 corresponding to electron density values that constitute x . The improved estimate of
 10 electron density profile x_a based on assimilation of measurement y into the NeQuick
 11 model profile x_b is given by (Angling and Cannon, 2004),

$$12 \quad x_a = x_b + K(y - Hx_b) \quad (2)$$

13 where K is the Kalman gain which can be determined as

$$14 \quad K = BH^T (HBH^T + R)^{-1} \quad (3)$$

15 In equation (3), B and R are the background and observation covariance matrices,
 16 respectively, while superscripts T and -1 denote transpose and inverse of the matrix,
 17 respectively.

18 In general, for n values of y within a period of 15 minutes and horizontal grid cell having
 19 geographic longitude and latitude spans of 5 and 4 degrees, respectively, equations 2
 20 and 3 can be written as

$$21 \quad x_a^i = x_b^i + K^i (y^i - H_i x_b^i) \quad (4)$$

22 and

$$23 \quad K^i = B_i H_i^T (H_i B_i H_i^T + R_i)^{-1} \quad (5)$$

24 respectively, where $i = 1, 2, \dots, n$.

1 As in Yue et al. (2007), measurement noise values w_i can be considered as white noise
 2 with zero expectation so that R_i in equation 5 is

$$3 \quad R_i = \text{var}(w_i) = c_r y_i^2, \quad (6)$$

4 where $c_r = 0.01$ and y_i is the i^{th} observation which is assimilated.

5 The background error was considered so that p by p matrix B_i consists of elements
 6 determined as (Yue et al., 2007),

$$7 \quad B_i(u, v) = c_b x_b^i(u) x_b^i(v) e^{\frac{-H_i(u)}{L_i(u)}} \quad (7)$$

8 where $c_b = 0.001$, $u = 1, 2, 3, \dots, p$, and $v = 1, 2, 3, \dots, p$. Following Bust et al. (2004),
 9 the distances $L_i(u)$ for scaling down $H_i(u)$ were considered as 20 km in E- and F-regions
 10 and 500 km in the plasmasphere. This implies that

$$11 \quad \frac{H_i(u)}{L_i(u)} = \begin{cases} \frac{H_i(u)}{20}, & \text{for } \text{height} \leq 600 \text{ km} \\ \frac{H_i(u)}{500}, & \text{for } \text{height} > 600 \text{ km} \end{cases} \quad (8)$$

12 Equation 4 corresponds to a specific grid cell and assimilation time window. This
 13 approach reduces the huge demand for computational resources especially when all the
 14 grid cells are considered at once as mentioned in Rodgers, (2000). This study termed
 15 the filtering as indicated in equation 4, as classical Kalman filtering due to its similarity to
 16 the application of the same in classical mechanics (e.g., prediction of river floods and
 17 tracking/navigation of ships and spacecrafts).

18 It is important to emphasize that y_i can be obtained from any of the 5 data sources
 19 discussed in section 2. The y values obtained from ground-based GPS receivers were
 20 treated similar to the TEC measurements of ionosonde and COSMIC RO which are
 21 considered vertical. This was done by limiting y values obtained from GPS receivers to
 22 slant TEC (STEC) observed at very high elevation angles ($>60^\circ$). Moreover, the
 23 ionospheric pierce points associated with the STEC were restricted to that of the

1 specific spatial grid cell considered. The first advantage of this procedure is
2 minimization of multipath effects on TEC observations and the second is rendering
3 simplicity to the assimilation process (y occupies one horizontal grid cell). In future we
4 might adopt the method described in Angling and Cannon (2004) to treat low elevation
5 angle TEC observations that cross several horizontal grid cells.

6 Since NeQuick model can yield electron density profile for heights starting from about
7 60 to 20,200 km (approximate GPS satellite altitude), the altitudinal intervals for
8 computing electron densities (x'_b in equation 4) were varied in this range. These
9 altitudinal intervals which constitute elements of H_i were set based on the known typical
10 vertical electron density profile as follows; in E- and F-regions (<600 km), electron
11 densities were computed at intervals of 10 km, for altitude region of 600 – 2000 km, the
12 interval was increased to 50 km and above 2000 km, the interval was further increased
13 to 2,000 km. Therefore, for the case of ground-based GPS receiver TEC, all the
14 elements of H_i were non zero.

15 In order to account for lack of consideration of the entire electron density profile within
16 the altitude range of 60 – 20,200 km during determination of y_i associated with TEC data
17 from Swarm and COSMIC satellites, COSMIC RO, and ionosondes, some elements of
18 H_i were set to zero. For instance, while considering measurements associated with
19 ionosonde and COSMIC RO, elements of H_i corresponding to heights >700 and >800
20 km, respectively were set to zero. For the case of Swarm A and C which fly at altitude
21 ~460 km, elements of H_i corresponding to heights below this altitude were set to zero.
22 While for Swarm B and COSMIC satellites, elements of H_i corresponding to heights
23 <510, and <800 km, respectively were set to zero.

24 It can be deduced from the sentence preceding equation 4 that TEC data assimilations
25 were done at horizontal grid cells which contained TEC observations. The influence of
26 TEC data assimilation at horizontal grid cells which lacked TEC data were achieved
27 through successive corrections method (Bergthorsson and Döös, 1955; Rodgers, 2000;
28 Bratseth, 1986).

1 4. The Successive Corrections Method

2 In order to correct NeQuick model generated electron density profile at horizontal grid
3 cell d based on assimilation results x_a^f ($f = 1, 2, 3, \dots, F$) in the nearest neighborhood
4 of d , the successive corrections method described in Bratseth, (1986) and Rodgers,
5 (2000) was applied after modifying it as,

$$6 \quad x_a^d = x_b^d + \left(\frac{1}{F}\right) \times \sum_f \times 10^{-r} \times (x_a^f - x_b^f), \quad (9)$$

7 where x_a^d is the corrected electron density profile, x_b^f is the background electron density
8 profile associated with x_a^f , and x_b^d is the background electron density profile at the
9 horizontal grid cell d . In equation 9, the expression $\left(\frac{1}{F}\right)$ in the second term was
10 introduced in order to obtain the average effect of assimilations at F grid cells in the
11 nearest neighborhood of grid d . Overall, simplification of the expression that constitutes
12 the second term in equation 9 yields small quantities. These small quantities either
13 increase or reduce elements (depending on the sign of $(x_a^f - x_b^f)$) of the NeQuick model
14 generated electron density profile, x_b^d at grid d .

15 Although the expression $(x_a^f - x_b^f)$ in equation 9 contains elements which are much
16 lower than typical NmF2 value ($\sim 10^{12}$ electrons/m²), the elements might still have a
17 factor of 10 raised to a number < 12 as a power. Based on this idea, the term 10^{-r} in
18 equation 9 was introduced to allow the quantity needed to correct background electron
19 density (x_b^d) to reduce as r increases. In fact, the term 10^{-r} in equation 9 dictates that at
20 large values of r , assimilation results do not (minimally) influence background electron
21 density profile at grid d . On the other hand, when r is small, the assimilation results
22 influence the background electron density profile maximally.

23 Actually, r quantifies effect of temporal ($d = f$) or spatial separation (at a fixed epoch)
24 between grid cells d and f . The consideration of r as spatial or temporal separation was

1 based on the idea that the local time difference between 2 locations separated by 15°
2 longitude is about 1 hour. After performing several trials, this study established that to
3 achieve smooth variations of electron densities spatially and temporarily, r values
4 should vary in steps of 0.25. Moreover, since elements in the expression $(x_a^f - x_b^f)$ are
5 expected to be small (\leq hundreds) compared to typical NmF2, the first r value was
6 assigned to 1. Equation 10 describes the variation of r as a function of longitudinal
7 difference between cells d and f ($d_{lon}(f)$), latitudinal difference between cells d and f
8 ($d_{lat}(f)$), and time difference between epoch with observation data and that which lacked
9 observation data ($dt(f)$).

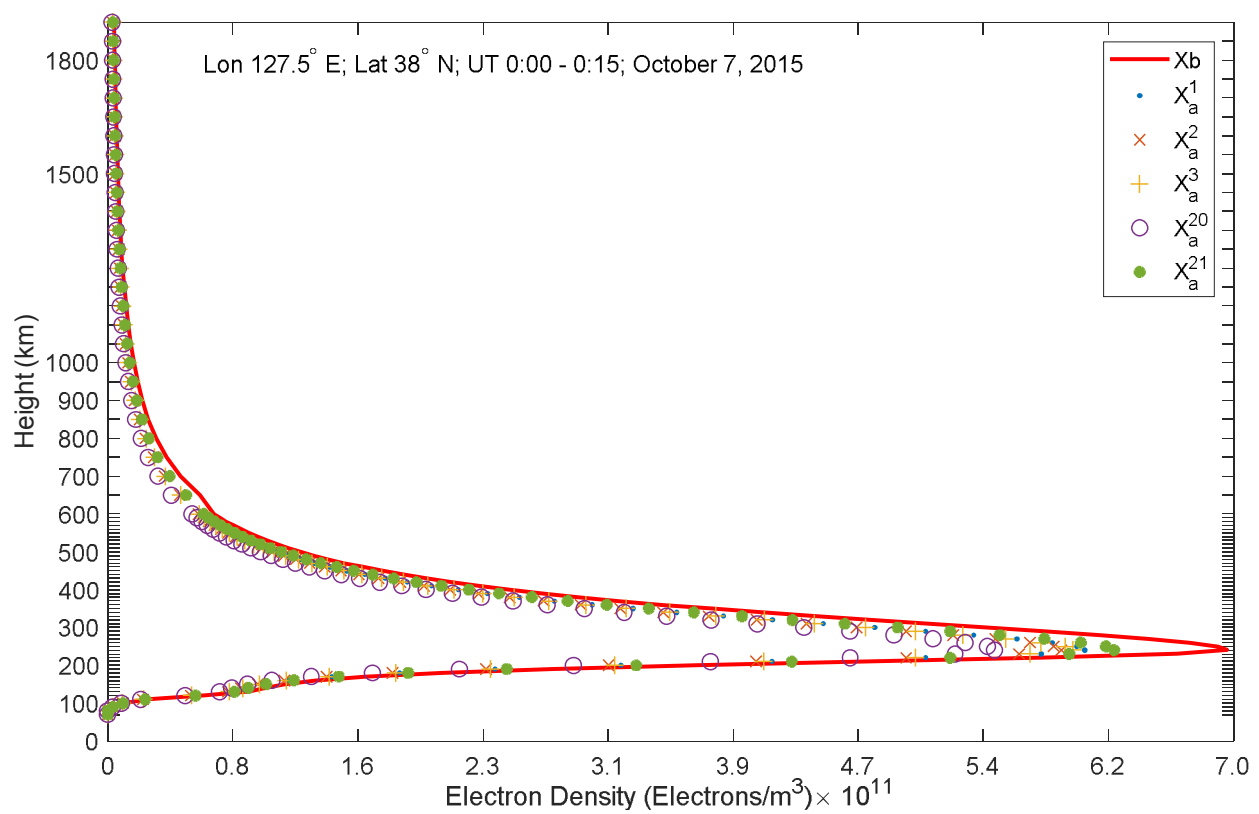
$$10 \quad r = \begin{cases} r_f (4 \times (i-1) < |d_{lat}(f)| \leq 4 \times i) = 1 + (i-1) \times 0.25; & \text{for } |d_{lon}(f)| < 5 \text{ and } |dt(f)| < 15 \\ r_f (5 \times (i-1) < |d_{lon}(f)| \leq 5 \times i) = 1 + (i-1) \times 0.25; & \text{for } |d_{lat}(f)| < 4 \text{ and } |dt(f)| < 15 \\ r_f (15 \times (i-1) < |dt(f)| \leq 15 \times i) = 1 + (i-1) \times 0.25; & \text{for } |d_{lon}(f)| < 5 \text{ and } |d_{lat}(f)| < 4 \end{cases} \quad (10)$$

11 where the two vertical bars represent magnitude and i is one of the positive integers
12 which was specified after knowing the spatial or temporal difference between grid cells
13 d and f . For example, when all conditions set in the top row of the right hand side of
14 Equation 10 are satisfied and $|d_{lat}(f)| = 6$ degrees, i will take value of 2.
15 Then, $r = r_f(4 < |d_{lat}(f)| \leq 8) = 1 + (2-1) \times 0.25 = 1.25$. Generally, at a particular assimilation
16 time window, all grid cells that lacked observation data were corrected in two ways. In
17 the first case, $d_{lon}(f)$ was restricted to ≤ 5 degrees, while r varied with $d_{lat}(f)$ as in the top
18 expression in right hand side of equation 10. In the second case $d_{lat}(f)$ was restricted to
19 ≤ 4 degrees, while r varied with $d_{lon}(f)$ as in the middle expression in right hand side of
20 equation 10. Concerning corrections at a particular grid cell ($d = f$) for epochs that
21 lacked observation data, the r values varied with $dt(f)$ as in the bottom expression in the
22 right hand side of equation 10.

23 5. Results and discussions

24 5.1 An example of data assimilation process

1 Figure 3 presents an example of assimilation result ($x_a^1, x_a^2, \dots, x_a^n$) based on
 2 equation 4 and TEC observed by ground-based GPS receivers on October 7, 2015. The
 3 data assimilated were those at grid cell centered at longitude and latitude 127.5° E and
 4 38° N, respectively as well as time interval 0:00 – 0:15 UT. In this assimilation window,
 5 we considered only 21 TEC observations ($n = 21$) to be assimilated. For clarity, we only
 6 present in Figure 3 $x_a^1, x_a^2, x_a^3, x_a^{20}$, and x_a^{21} which are associated with the first three
 7 and the last two observed TEC values. The red line in Figure 3 represents background
 8 electron density ($x_b^1, x_b^2, x_b^3, x_b^{20}, x_b^{21}$) obtained from NeQuick model. While
 9 implementing equation 4, we set $x_b^1 = x_b^2 = \dots = x_b^n$. This implies that the 21
 10 observed TEC values were treated as scalars and assimilated in a manner similar to
 11 the recursive approach as in Grewal and Andrews, (2001).



12
 13 **Figure 3:** Electron density profile obtained from NeQuick model (red) and improved
 14 profiles ($\cdot, \times, +, o, *$) associated with assimilation of some TEC values within spatial grid

1 cell centered at longitude and latitude 127.5° E and 38° N, respectively. The date and
2 time interval associated with the data plotted are indicated on top of the panel.

3 Based on the similarity with the recursive approach, we considered x_a^{21} associated with
4 the last assimilated observed TEC value as the assimilation result for the specific
5 assimilation window. We need to mention that the peak electron densities computed
6 from x_a^{21} and x_b^{21} and were 6.0×10^{11} and 8.5×10^{11} electrons/m³, respectively. These
7 peak electron densities can be converted to foF2 using the expression (Davies, 1990),

$$8 \quad foF2 = \sqrt{\frac{NmF2}{1.24 \times 10^{10}}} \quad (11)$$

9 yielding 6.96 and 7.41 MHz, respectively. These two values of foF2 can be compared
10 with 5.94 MHz obtained from the ionosonde at IC437 (Lon 127°, Lat 36°) during the date
11 and assimilation window indicated in Figure 3. The comparison reveals that the
12 difference between foF2 obtained by assimilation procedure and the observed is smaller
13 than that between foF2 obtained from NeQuick model and the observed. For
14 generalization purposes several test scenarios were performed for the entire period
15 under study.

16 **5.2 Assimilation Test Scenarios**

17 The test scenarios presented in this subsection were validated at horizontal grid cells
18 centered at geographic latitude (longitude) (i) 26° (122.5°), (ii) 34° (137.5°), and (iii) 38°
19 (127.5°), (iv) 33.4°(126.3°), (v) 26.3°(127.8°), and (vi) 39.6°(115.9°). The validation at
20 grid cells (i) and (ii) were done using TEC data obtained from GPS receiver at TCMS
21 and foF2 data obtained from ionosonde at TO536, respectively, while that at (iii) was
22 done using TEC data obtained from GPS receiver at YONS as well as foF2 data
23 obtained from ionosonde at IC437. Moreover, the validation at grids (iv) and (v) were
24 done using foF2 data obtained from OK426 and JJ433, while the validation at grid (vi)
25 was done using TEC data obtained from BJFS. It should be noted that validation station
26 data were not used during assimilation.

1 **5.2.1 Assimilation of Ground-based GPS receiver TEC**

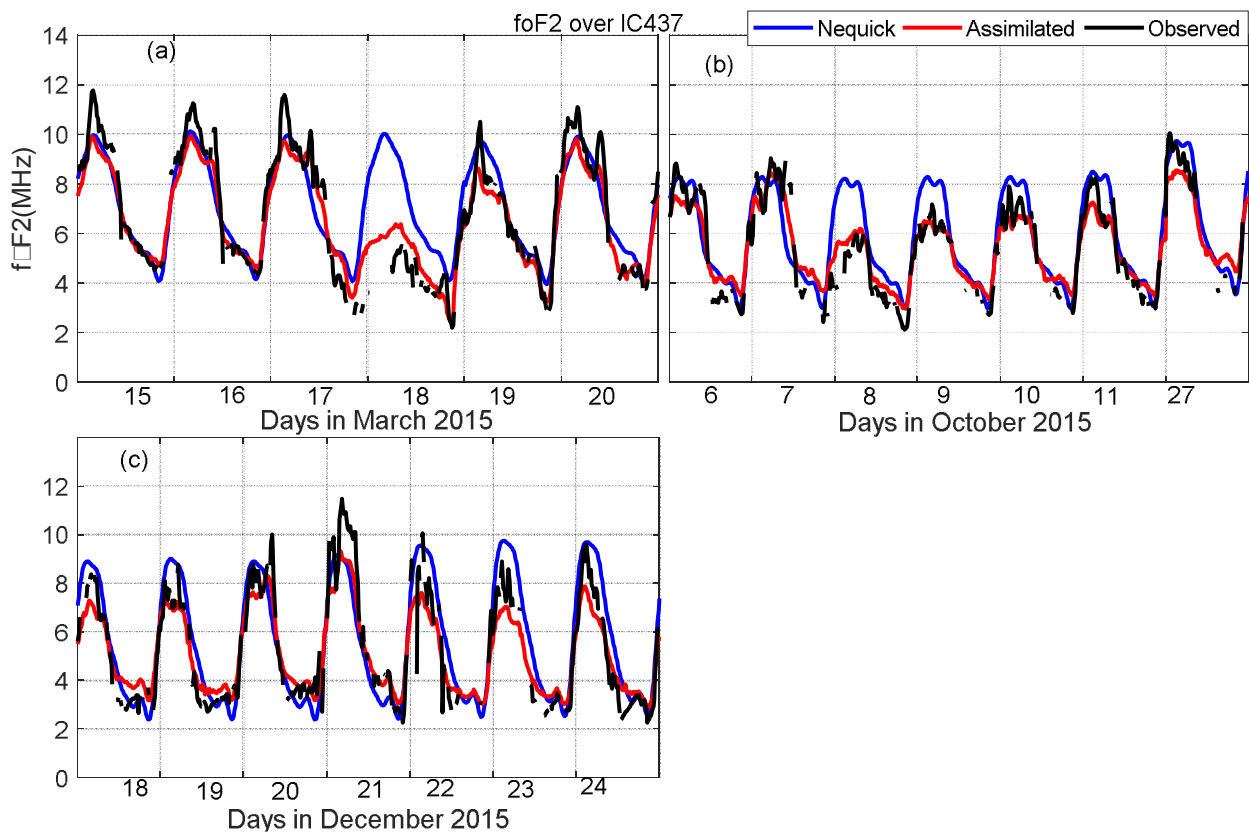
2 We assimilated ground-based GPS receiver derived TEC to the NeQuick model using
3 equation 4. The foF2 derived from the assimilation results over IC437 during March 15 -
4 20, October 6 – 11, 27, and December 18 - 24, 2015 are presented in Figure 4, panels
5 (a), (b), and (c), respectively. The corresponding foF2 observed by the ionosonde at the
6 station as well as foF2 obtained from NeQuick model are superimposed. The blue, red,
7 and black colors in Figure 4 and later in Figures 5 and 7 represent parameters obtained
8 from NeQuick model, assimilation, and observation, respectively.

9 Figures 5 (a) - (d) present TEC over YONS obtained from assimilation, NeQuick model,
10 and GPS receiver station during March 15 - 20, June 4, 21 - 26, October 6 – 11, 27, and
11 December 18 - 24, 2015, respectively. The increase and reduction in comparison to a
12 background value of observed ionospheric parameters during geomagnetic storms are
13 usually termed as positive and negative ionospheric storm effects, respectively
14 (Buonsanto, 1999). As mentioned in section 2, this study associated the ionospheric
15 parameters during March 15, June 4, October 27, and December 18, 2015 when $K_p \leq 3$
16 with background values. It can be deduced from Figures 4 (c), 5 (b) and (d) that values
17 of ionospheric parameters increased during the main phases of geomagnetic
18 disturbances in June and December solstices when compared to those on quiet days in
19 these seasons. Moreover, Figures 4 (a), (b), 5 (a) and (c) clearly show that values of
20 ionospheric parameters reduced significantly during the main phases of geomagnetic
21 disturbances in March and September equinoxes when compared to those on quiet
22 days in these seasons. Since detailed discussions about the physical mechanisms
23 responsible for the generation of positive and negative ionospheric storm effects are out
24 of the scope of the current study, interested readers may refer to the previous studies
25 (e.g., Buonsanto, 1999; Mendillo and Klobuchar, 2006) for such discussions.

26 Generally, Figures 4 and 5 show that the assimilation yielded ionospheric parameters
27 which are in most cases closer to the observed parameter than to those generated from
28 NeQuick model. Therefore, the assimilation process yields ionospheric parameters
29 which depict the response of the ionosphere to geomagnetic disturbance. Another

1 general feature of Figures 4 and 5 is that assimilation results and the observed data
2 exhibited daily/diurnal variability, which is almost not present in the climatological
3 NeQuick model values. However, visual inspection of Figure 4 shows some cases (e.g
4 panel (c) on December 18 and 24) where NeQuick model results are closer to the
5 observed data compared to assimilation results. These isolated cases might result
6 because the data assimilated are obtained using GPS receiver while the observation
7 data presented in Figure 4 are obtained using ionosonde. The inherent discrepancy in
8 the instruments might manifest in the observed cases of assimilation results not
9 performing well. The overall statistical analysis presented in Figure 6 (b) confirms that
10 these are isolated cases.

11



12

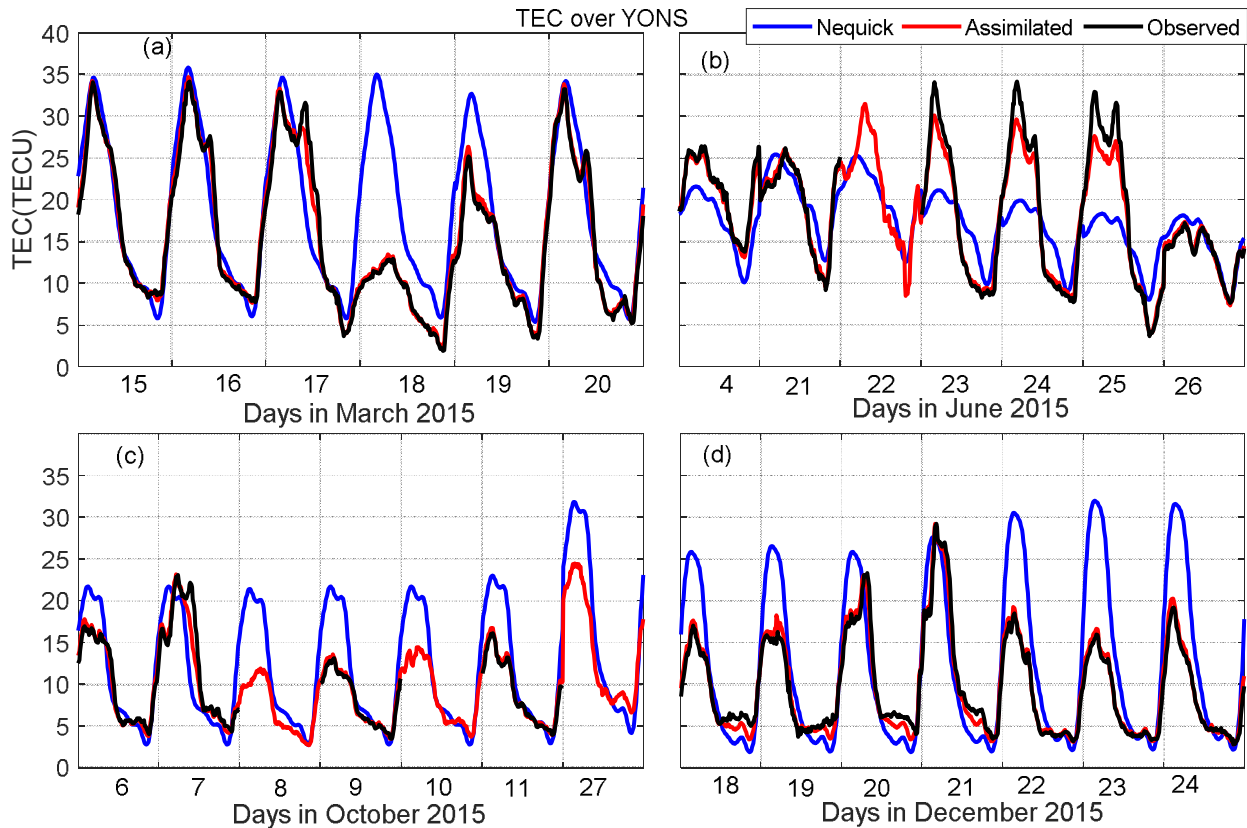
13 Figure 4: Panels (a), (b), and (c) present variation of foF2 during March 15 - 20, October
14 6 - 11, 27, and December 18 - 24, 2015, respectively over IC437. The blue, red, and

1 *black colors represent NeQuick model generated parameter, assimilation result, and*
2 *observed parameter, respectively.*

3

4

5



6

7 Figure 5: Panels (a) - (d) present variation of TEC during March 15 - 20, June 4, 21 -
8 26, October 6 - 11, 27, and December 18 - 24, 2015, respectively over YONS. The blue,
9 red, and black colors represent NeQuick model generated parameter, assimilation
10 result, and observed parameter, respectively.

11

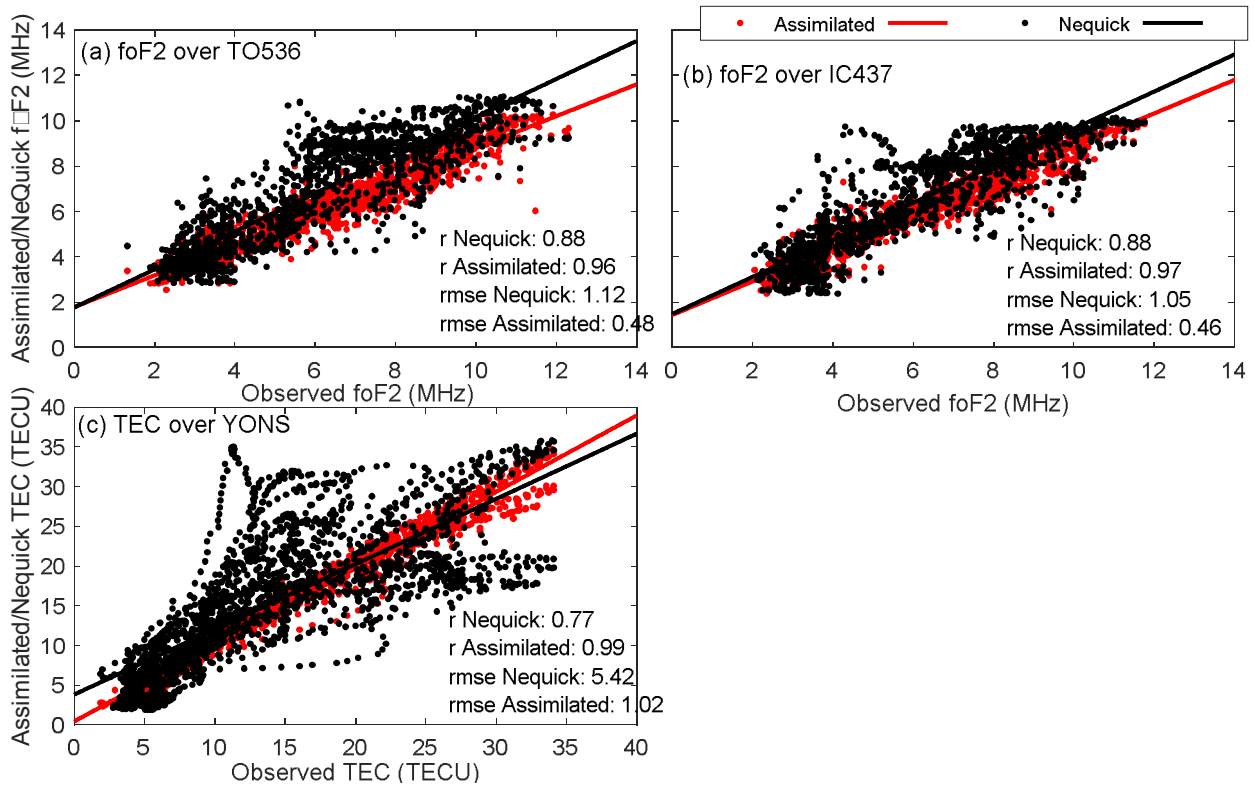
12 Figures 6 (a) - (c) present the scatter plots of NeQuick model generated ionospheric
13 parameter (red color) and assimilation results (black color) as a function of coincident

1 observed parameter over TO536, IC437, and YONS, respectively. It should be noted
2 that the data plotted in Figure 6 is the same as that in Figures 4 and 5. The correlation
3 coefficients r , and root mean squared error (RMSE) associated with the data plotted are
4 indicated on the respective panels. It can be seen in Figure 6 that r value associated
5 with assimilation result parameter over a particular station is always higher than that of
6 NeQuick model. Moreover, the RMSE value associated with assimilation result
7 parameter over a particular station appear significantly improved (reduced) compared to
8 that associated with NeQuick model. In fact, the improvement percentage (IP) of the
9 RMSE values were determined as

$$10 \quad IP = \frac{NQ_E - ASM_E}{NQ_E} \times 100\% \quad (12)$$

11 where NQ_E and ASM_E represent RMSE values associated with NeQuick model and
12 assimilation result, respectively. The IP over TO536, IC437, and YONS were 69, 56,
13 and 81 % respectively.

1



2

3 *Figure 6: Panels (a) and (b) present scatter plots of foF2 obtained from NeQuick model*
4 *(red color) and assimilation result (black color) as a function of coincident observed foF2*
5 *over TO536 and IC437, respectively. Panel (c) presents TEC obtained from NeQuick*
6 *model and assimilation result as a function coincident observed TEC over YONS. The*
7 *observations are those that fall within the study period*

8 The RMSE improvement percentage values ($\geq 56\%$) we obtained in this study are
9 higher than the 44% of Mengist et al. (2019) when they investigated the performance of
10 Ionospheric Data Assimilation Four-Dimension technique over Korea and adjacent
11 areas, considering International Reference Ionosphere model as the background model.
12 The study by Mengist et al. (2019) was done during both geomagnetic quiet and
13 disturbed days (March 15 – 18, 2015). The limitation of the vertical grids to altitude of
14 $\sim 1,336$ km in Mengist et al. (2019) might contribute to the low RMSE improvement
15 percentage obtained in their study compared to that of the current study. The study on
16 imaging South African regional ionosphere using 4D-var technique by Ssessenga et al.

1 (2019) might not reasonably estimate TEC up to altitude of GPS satellites since it
2 limited the vertical grid to altitude of 1,336 km.

3 The results presented in Figures 4 and 6 signify that assimilation of TEC data obtained
4 from ground-based GPS receiver to NeQuick model can be helpful in determining fairly
5 well foF2 over a location that does not have ionosonde station.

6 **5.2.2 Assimilation of TEC obtained from Ionosonde stations**

7 After assimilating ionospheric TEC data obtained from ionosonde stations to the
8 NeQuick model, the validation of the assimilation exercise was done using TEC data
9 obtained from YONS. It should be noted that most records of ionosonde stations did not
10 have available TEC data with the exception of IC437 which belongs to the same spatial
11 grid cell (ii) as YONS. Figure 7 presents the variations of TEC obtained from
12 assimilation (red) over YONS during the period under study. Superimposed over the
13 figure are the corresponding TEC obtained from NeQuick model as well as observed
14 TEC data obtained from GPS receiver over YONS. Figure 7 clearly shows similar
15 observations that were deduced from Figures 4 and 5. Overall, the TEC obtained by
16 assimilation closely follows the observed TEC.

17

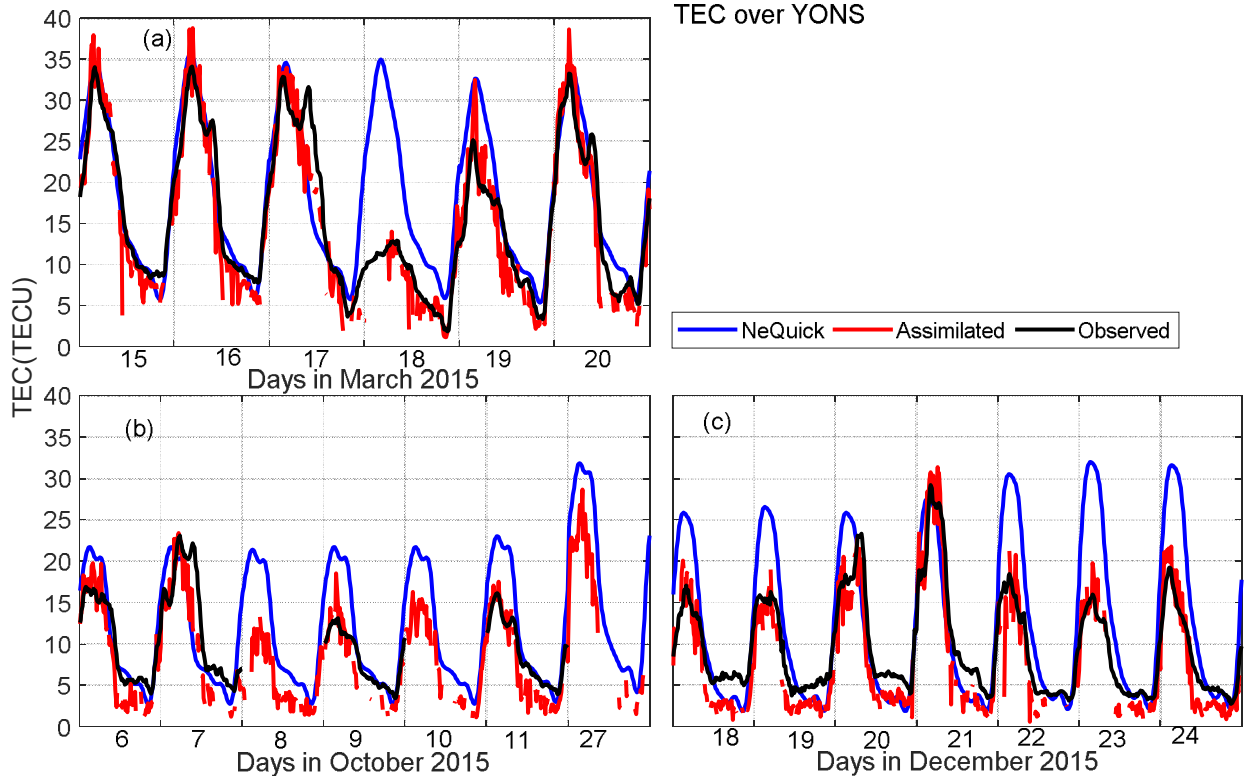
18

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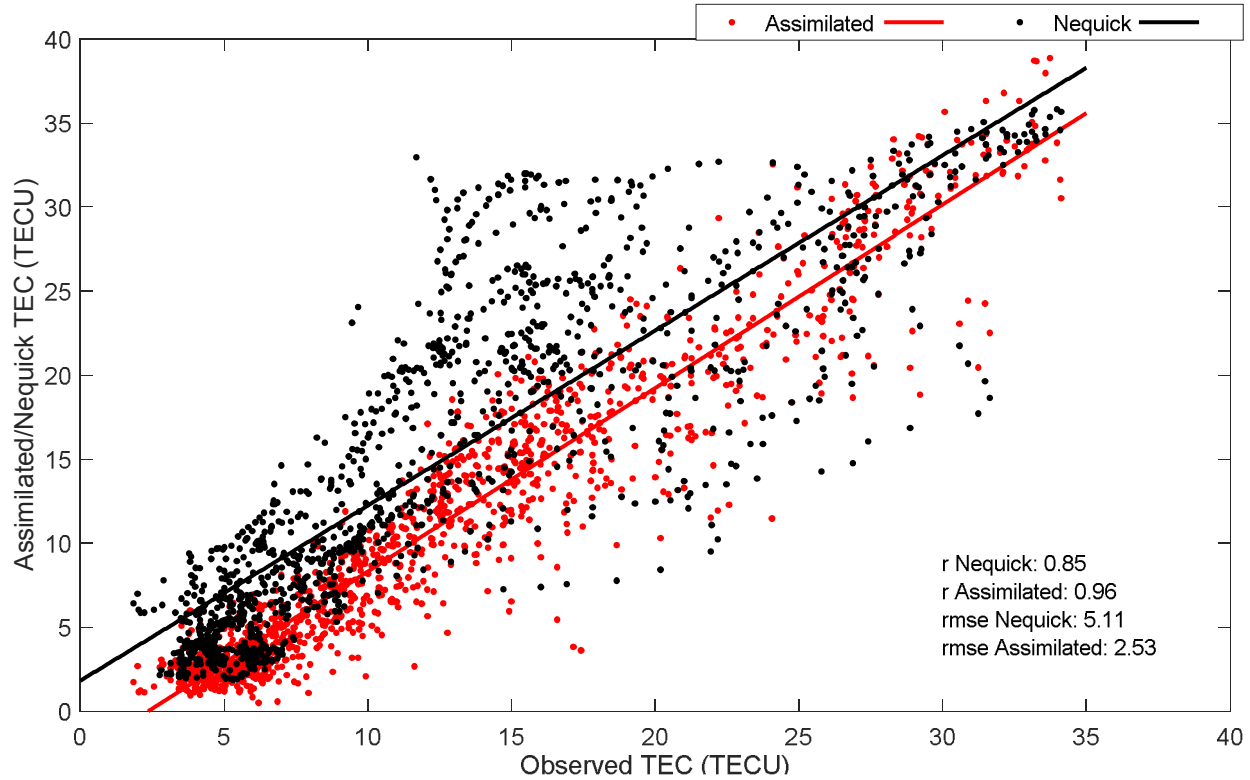
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22



1
 2 *Figure 7: Panels (a) – (c) present TEC obtained from NeQuick model (blue),*
 3 *assimilation (red), and observed by ground-based GPS receiver (black) during March*
 4 *15 - 20, October 6 - 11, 27, and December 18 - 24, 2015, respectively over YONS.*

5 In order to quantify how well the assimilation has improved estimation of TEC over
 6 YONS, we present in Figure 8 a scatter plot of TEC obtained from assimilation (black)
 7 and NeQuick model (red) as a function of coincident observed TEC over YONS. On the
 8 figure, the r and RMSE associated with TEC obtained from assimilation and NeQuick
 9 model are indicated. The r values portray that the TEC obtained from assimilation
 10 correlates with observed TEC better than that obtained from background model. By
 11 performing assimilation, the RMSE improved by ~50 %. This low improvement
 12 compared to that associated with assimilation of ground based GPS receiver data could
 13 be due to lack of inclusion of TEC above 700 km during assimilation. In addition,
 14 although electron density can be computed by NeQuick model up to an altitude of 700
 15 km, the ionosonde observations may not in some cases reach this altitude. This might
 16 partly explain why the assimilation TEC data in Figure 7 appears to be noisy.



1
 2 Figure 8: Scatter plot of TEC obtained from NeQuick model (red color) and assimilation
 3 result (black color) as a function of coincident observed TEC over GPS receiver station
 4 at YONS. The data plotted are the same as that in Figure 7.

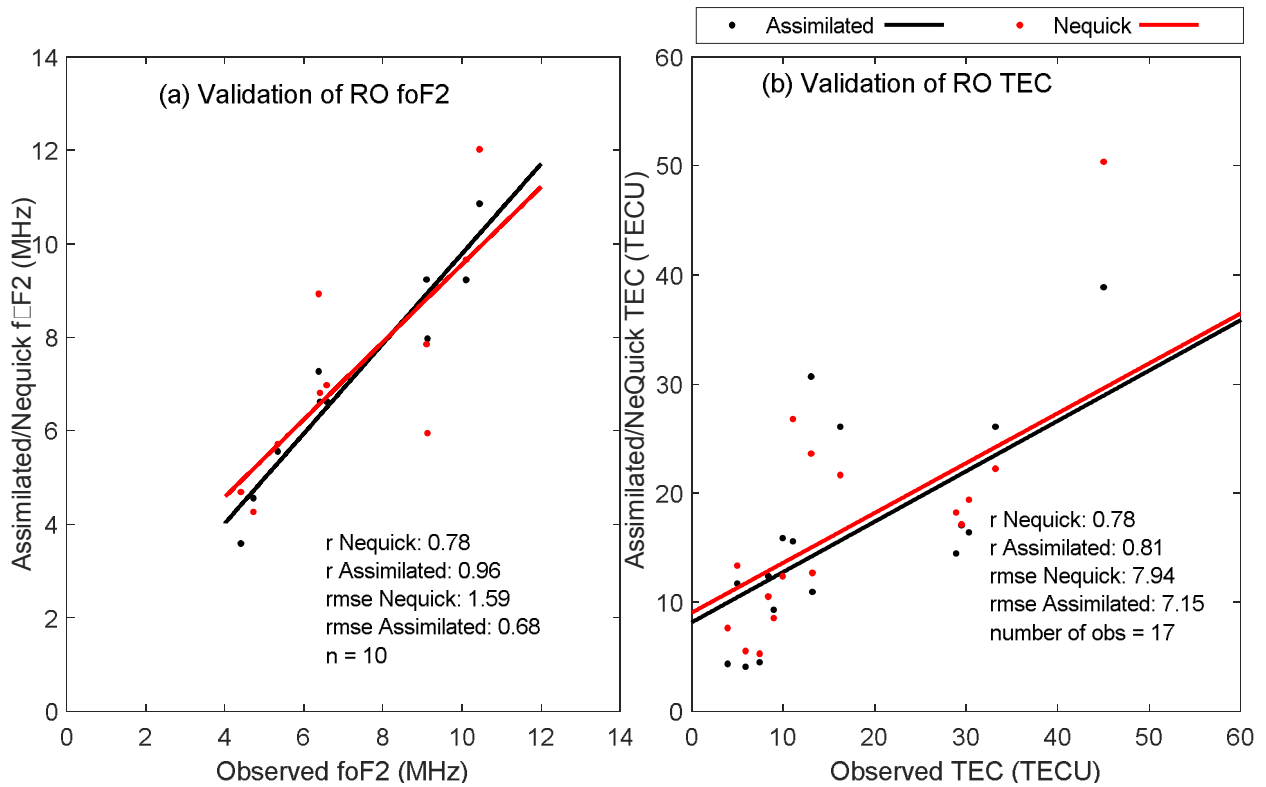
5
 6 It needs to be noted that the 50 % increment signifies that over locations which do not
 7 have ground-based GPS receivers, assimilation of TEC obtained from ionosondes into
 8 NeQuick model can be helpful in improving estimation of TEC data that would be
 9 measured by ground-based GPS receivers.

10
 11 **5.2.3 Assimilation of TEC obtained from COSMIC RO**

12 Due to the scarcity of RO TEC data, we validated the results of assimilation of the data
 13 into NeQuick model with foF2 obtained from all the ionosonde stations considered in
 14 this study. Moreover, validations were done using TEC observed over Japan (KGNI),

1 South Korea (YONS), Taiwan (TCMS), and China (BJFS). Figure 9 (a) presents a
2 scatter plot of foF2 obtained from assimilation (black) and NeQuick model (red) as a
3 function of coincident observed foF2 over the ionosonde stations, while Figure 9 (b)
4 presents TEC obtained from assimilation and NeQuick model as a function of coincident
5 observed TEC over the IGS stations. The r and RMSE associated with data plotted in
6 panels of Figure 9 are shown on the respective panels. Also indicated on the panels of
7 Figure 9 are the numbers of observed data which are coincident to assimilation results.
8 Despite considering 27 days in the year 2015 and all 4 ionosonde stations, there were
9 only 10 observations of foF2 values which were coincident with assimilation results. For
10 the case of validation with TEC data, there were only 17 observations which were
11 coincident with assimilation results.

12 Figure 9 exhibits that the assimilation of COSMIC RO TEC greatly improves estimation
13 of foF2 and TEC since the r values associated with assimilation results are higher than
14 those associated with NeQuick model. In fact, the RMSE improvement percentages for
15 foF2 and TEC are 57 and 10 %, respectively. The percentage associated with TEC data
16 is much less compared to that of foF2, maybe due to the limitation of COSMIC RO
17 electron density profile altitude of ~800 km.



1
2 *Figure 9: Panel (a) presents scatter plot of foF2 obtained from NeQuick model (red) and*
3 *assimilation (black) as a function of coincident observed foF2 over the ionosonde*
4 *stations considered in this study. Panel (b) presents scatter plot of TEC obtained from*
5 *NeQuick model and assimilation as a function of coincident observed TEC over KGNI,*
6 *TCMS, YONS, and BJFS GPS receiver stations. The data plotted are those on the days*
7 *of the study period.*

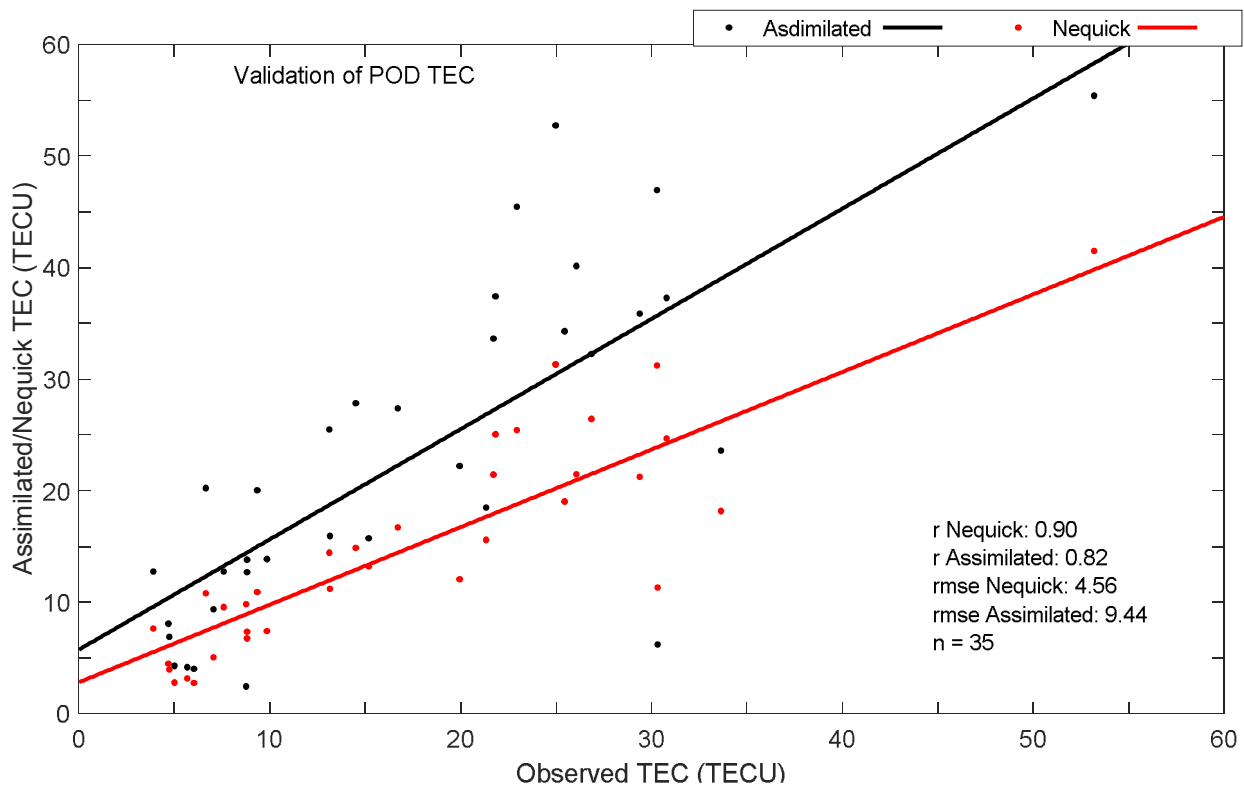
8 Based on the observations and discussions associated with Figure 9, the assimilation of
9 COSMIC RO TEC seems to improve estimation of foF2 and TEC ionospheric
10 parameters.

11 **5.2.4 Assimilation of TEC obtained from GPS receivers onboard Swarm and** 12 **COSMIC satellites**

13 The results of assimilation of TEC obtained from GPS receivers onboard Swarm and
14 COSMIC satellites were validated with ground-based GPS receivers over Japan
15 (KGNI), South Korea (YONS), Taiwan (TCMS), and China (BJFS). Similar to Figure 9,

1 Figure 10 presents the scatter plot of NeQuick model TEC (red color) and assimilation
 2 TEC (black color) as a function of coincident observed TEC over the ground-based GPS
 3 receiver stations. Indicated on Figure 10 are the r and RMSE associated with the data
 4 plotted in the figure as well as the number of coincident assimilation TEC and observed
 5 TEC over the GPS receiver stations. Even though 27 days in the year 2015 and TEC
 6 data from GPS receiver stations located in 4 different countries were considered, there
 7 were still few (35) coincident data, as indicated in Figure 10. This observation may be
 8 due to the fact that LEO satellites pass over a particular location reoccurs after several
 9 days.

10 Figure 10 reveals that the assimilation of TEC obtained from GPS receivers onboard
 11 LEO satellites yields lower correlation coefficient compared to that associated with the
 12 NeQuick model. Actually, the RMSE deteriorated by $\sim 107\%$.



13
 14 *Figure 10: Scatter plot of TEC obtained from NeQuick model and assimilation as a*
 15 *function of coincident observed TEC over GPS receiver stations at KGNI, TCMS,*
 16 *YONS, and BJFS. The data plotted are those on the days of the study period.*

1 The poor estimation of ionospheric parameters by the assimilation of TEC obtained from
2 GPS receivers onboard LEO satellites need to be investigated further. However, we
3 tentatively attribute this poor performance to the (i) dynamics of the receiver which
4 might have not been considered in computing the POD TEC (ii) limitation of the
5 assimilation technique.

6 In a practical application situation, assimilation of TEC data would depend on
7 precedence of the data source which can be set based on the results depicted in the
8 various test scenarios presented above. For instance, TEC data obtained from ground-
9 based GPS receiver would be given the highest precedence, followed by TEC data from
10 ionosonde, and lastly COSMIC RO TEC.

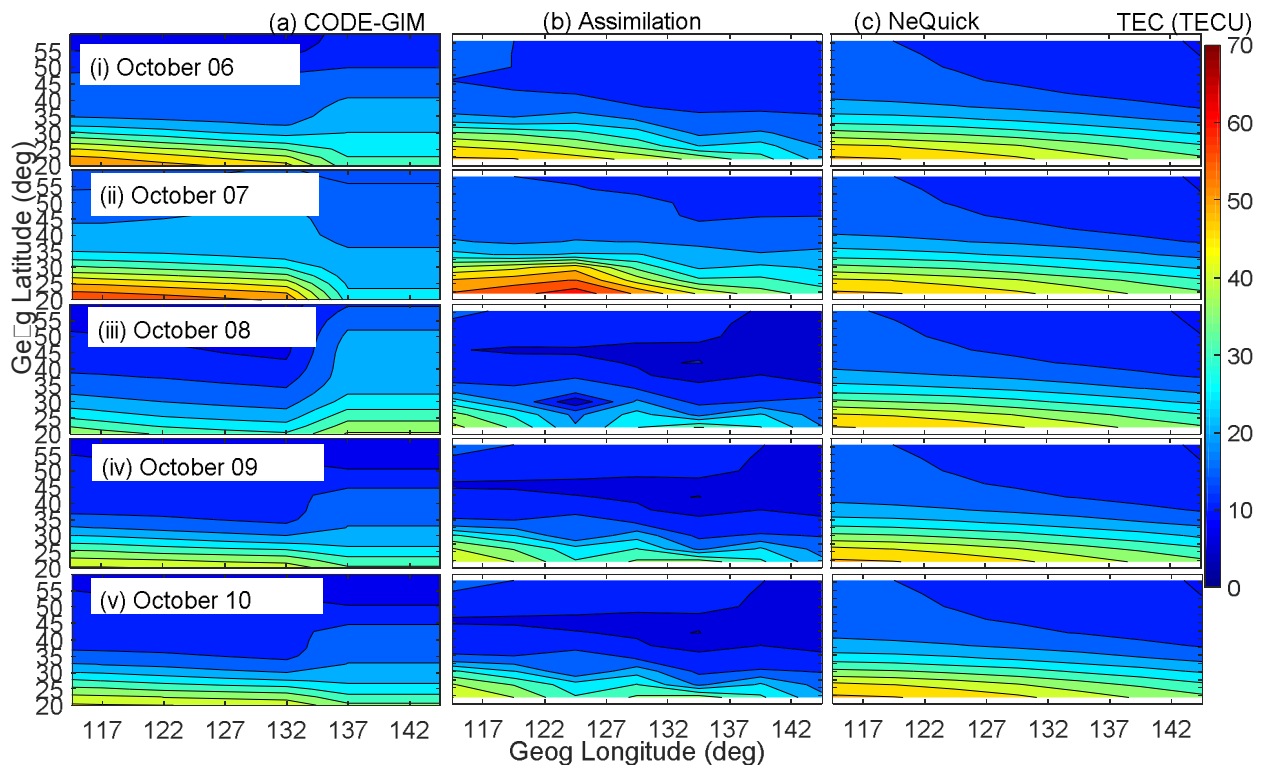
11 Based on the results from the test scenarios, for now we would not recommend
12 assimilation of TEC derived from GPS receivers onboard the LEO satellites to the
13 NeQuick model. If a horizontal grid cell does not have TEC data from any of the 3
14 recommended sources, the NeQuick model generated electron density profile at the cell
15 would be corrected as described in section 4. Examples of assimilation results obtained
16 from data assimilations followed by application of successive corrections method are
17 presented and compared with TEC data processed at the Center for Orbit
18 Determination in Europe (CODE) in section 5.3. As one of the international GPS service
19 (IGS) for geodynamics analysis centers, CODE provides daily Global Ionospheric TEC
20 data Maps (GIMs) at www.aiub.unibe.ch/download/CODE/.

21

22 **5.3 Validation of successive Corrections method**

23 This section presents in Figure 11 results where TEC data from all the ground-based
24 GPS receiver and ionosonde stations indicated in Figure 2 as well as COSMIC RO were
25 assimilated followed by successive corrections method to yield the final assimilation
26 result. Later in this section we also present in Figure 12 similar results, but where TEC
27 data from ionosonde stations at JJ433 and OK426 were not assimilated. These 2
28 stations appear to be suitable for validating further successive corrections method since

1 Figure 2 shows there were no ground-based GPS receivers within the grid cells that
 2 contain the stations. In Figure 11, panels in columns (a) – (c) present CODE GIMs, TEC
 3 obtained from assimilation result and NeQuick model, respectively. Panels in rows (i) -
 4 (v) present the TEC data at 5:00 UT (14:00 and 15:00 LT over Korea and Japan,
 5 respectively) when considerable ionization is expected during October 6 - 10, 2015,
 6 respectively. These dates were chosen to reveal the ionospheric changes before and
 7 during the main phase (October 6 – 7, 2015) of the storm as well as during and after the
 8 recovery phase (October 8 - 10).



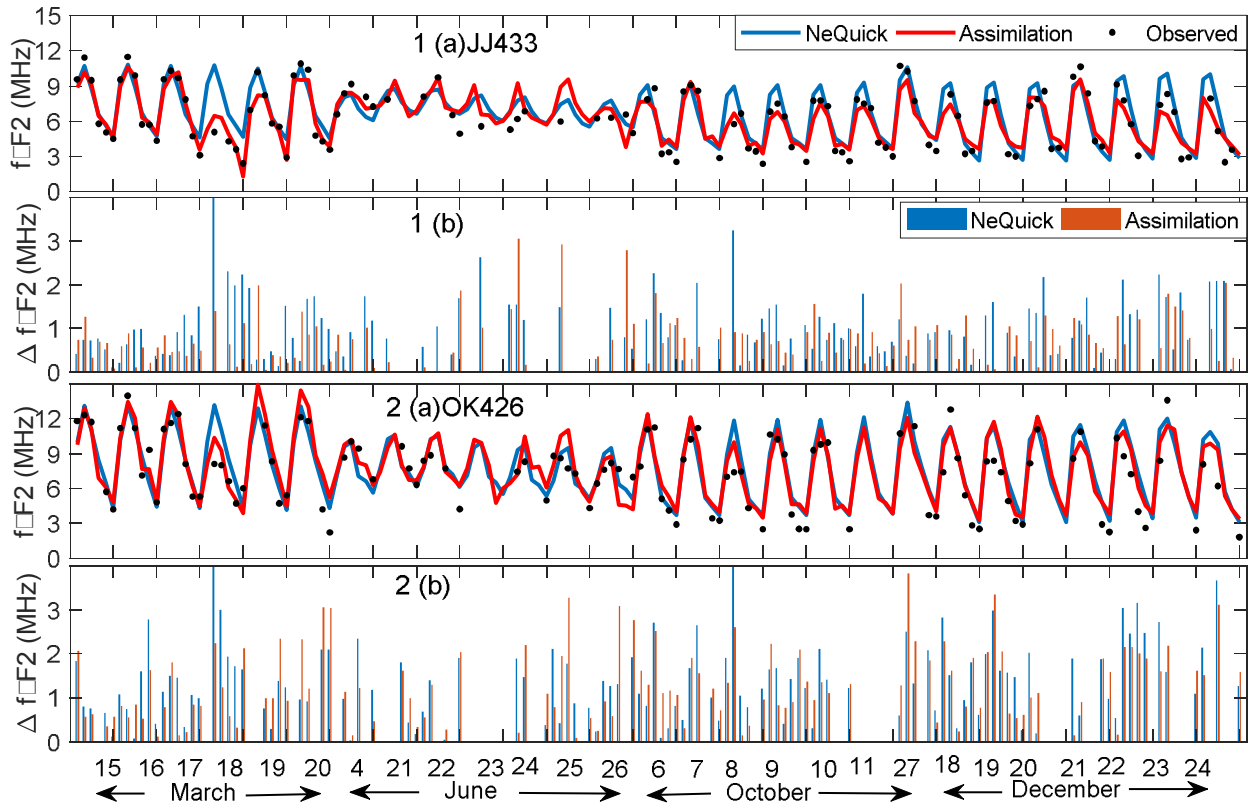
9

10 *Figure 11: Panels in columns (a) – (c) present TEC obtained from CODE GIMs,*
 11 *assimilation, and NeQuick model, respectively. Panels in rows (i) - (v) present the TEC*
 12 *data at 05:00 UT during October 6 - 10, 2015, respectively.*

13 It can be seen in Figure 11 that on October 7, 2015, TEC data from CODE and
 14 assimilation were the highest and reduced significantly on October 8, 2015. This
 15 observation is consistent with the results that were presented and discussed in section
 16 5.2 (see Figures 4 - 6), where the TEC values during the main phase of the storm on

1 October 7, 2015 (see Figure 1) were found to be higher than that during the recovery
2 phase of the storm on October 8, 2015. As expected, these variations in TEC data
3 during the main and recovery phases of the storm are not strongly reflected in the
4 NeQuick model presented in Figure 11, panels in column (c). Visual inspection of
5 panels in row (iii) of Figure 11 shows that at longitude $>132^\circ$, TEC data from CODE
6 GIMs are higher than that of assimilation and NeQuick. Since CODE GIMs are
7 constructed using a series of spherical harmonics functions whose coefficients are
8 determined using available TEC data from IGS stations (Schaer, 1999), CODE GIMs
9 TEC data over locations that lacked IGS stations may contain high error value.
10 Therefore, although TEC data from both CODE and assimilation seem to respond to
11 TEC changes due to occurrence of geomagnetic storm, TEC data from the two sources
12 may not perfectly correlate. Furthermore, although the resolution of the CODE GIMs
13 was changed from 2 hours to 1 hour on 19th October 2014, this hourly averaging might
14 still prevent the capturing of fine structures in the maps.

15 As mentioned before in this subsection, the successive corrections method was
16 validated further using foF2 obtained from ionosonde stations at JJ433 and OK426.
17 Panels 1 (a) and 2 (a) in Figure 12 present the foF2 obtained from NeQuick model (blue
18 line), assimilation results (red line), and ionosonde stations (black dots). The
19 magnitudes of the differences between foF2 obtained from (i) NeQuick model and (ii)
20 assimilation results and the observed, denoted as ΔfoF2 are presented in the panels 1
21 (b) and 2 (b) of the figure. It is important to mention that the data plotted in Figure 12 are
22 for the months and days in the month indicated on the horizontal axis of panel 2 (b). For
23 each day, the data were sampled at 4 hours interval. Particularly, the data
24 corresponding to 02:00, 06:00, 10:00, 14:00, 18:00, and 22:00 LT are plotted in Figure
25 12.



1
2 *Figure 12: Panels 1 (a) and 2 (a) show foF2 obtained from NeQuick model (blue line),*
3 *assimilation results (red line), and ionosonde stations (black dots) at JJ433 and OK426,*
4 *respectively. Panels 1 (b) and 2 (b) present the magnitudes of the differences between*
5 *foF2 obtained from NeQuick model (blue bars) and assimilation results (red bars) and*
6 *that observed at ionosonde stations at JJ433 and OK426, respectively.*

7 It can be seen in panels 1 (b) and 2 (b) of Figure 12 that the $\Delta foF2$ associated with
8 assimilation results are mostly smaller than those corresponding to NeQuick model. The
9 average $\Delta foF2$ associated with assimilation results over JJ433 and OK426 were
10 established as 0.79 and 1.30 MHz, respectively, while the average $\Delta foF2$ associated
11 with NeQuick results over JJ433 and OK426 were 1.04 and 1.40 MHz, respectively.
12 These results imply that over a particular station, the average $\Delta foF2$ associated with
13 assimilation reduces significantly compared to that associated with NeQuick model. The
14 high average $\Delta foF2$ and foF2 values over OK426 as depicted in Figure 12 might be
15 associated with the closeness of the station to the equatorial region where high
16 ionization and electro-dynamic processes occur. The sparse availability of ground-

1 based GPS receivers within the vicinity of OK426 as shown in Figure 2 might be
2 another reason for the high average Δf_oF_2 observed over the station. This is expected
3 since the effectiveness of successive corrections method decreases as distance from
4 locations of data increase.

5

6 **6. Conclusions**

7 We made effort to improve estimation of ionospheric parameters over Korea and
8 adjacent areas by employing classical Kalman filtering technique to assimilate TEC data
9 from various sources into the NeQuick model. Successive corrections method was
10 applied to spread the effect of TEC data assimilation at a given location to others that
11 lacked TEC observations. The results from different assimilation scenarios showed that
12 data assimilation of ground-based GPS derived TEC data can improve root mean
13 squared error (RMSE) associated with the model estimation by ≥ 56 %. Assimilation of
14 TEC measured by ionosonde stations can improve RMSE associated with the model
15 estimation of TEC data by ~ 50 %. The assimilation of TEC obtained from COSMIC RO
16 revealed RMSE improvement of ~ 10 %. Assimilation of TEC measured by GPS
17 receivers' onboard LEO satellites degraded the RMSE associated with the model
18 estimation by ~ 107 %, probably due to either the dynamics of the receivers or limitation
19 of the assimilation technique. Validation of our assimilation results with global
20 ionosphere TEC data maps processed at CODE revealed that both reproduced similar
21 TEC changes, showing response to a geomagnetic storm. However, TEC data from the
22 two sources may not perfectly correlate.

23 For practical applications, we propose the assimilation of TEC data into the NeQuick
24 model depending on the precedence of the data source which can be set based on the
25 results presented in this study. That is, TEC data obtained from ground-based GPS
26 receiver would be given the highest precedence, followed by TEC data from ionosonde,
27 and lastly COSMIC RO TEC.

1

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8 making their model available. Dst data is provided by the World Data Center for
9 Geomagnetism at Kyoto (<http://swdcwww.kugi.kyoto-u.ac.jp/>) and the Kp data is
10 provided by GFZ Potsdam (<ftp://ftp.gfz-potsdam.de/pub/home/obs/kp-ap/>). The
11 ionosonde observations were obtained from the website of the National Oceanic and
12 Atmospheric Administration (<http://www.swpc.noaa.gov/>), while ionPrf files used to
13 derive COSMIC RO TEC were obtained from COSMIC Data Analysis and Archive
14 Center (<http://cosmic-io.cosmic.ucar.edu/cdaac/index.html>). The RINEX files used in
15 this study were obtained from the University NAVSTAR Consortium website ([ftp://data-
16 out.unavco.org](ftp://data-out.unavco.org)). The global ionosphere TEC data maps processed at CODE were
17 obtained from www.aiub.unibe.ch/download/CODE/.

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19